

# Multi-disciplinary Measurement

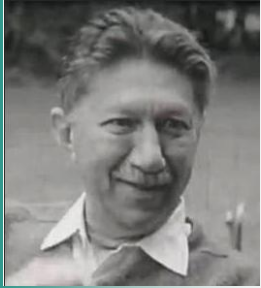
*Claes Fredö*

*Elisabet Blom*

# Root Cause Analysis: *Automotive style*

- **D0: Plan:**
  - Plan for solving the problem and determine the prerequisites.
- **D1: Use a Team:**
  - Establish a *team* of people with product/process knowledge.
- **D2: Describe the Problem:**
  - Specify the problem by identifying in quantifiable terms the who, what, where, when, why, how, and how many (5W2H) for the problem.
- **D3: Develop Interim Containment Plan:**
  - Define and implement containment actions to isolate the problem from any customer.
- **D4: Determine and Verify Root Causes and Escape Points:**
  - Identify all applicable causes that could explain why the problem has occurred. Also identify why the problem was not noticed at the time it occurred. All causes shall be verified or proved. One can use [five whys](#) or [Ishikawa diagrams](#) to map causes against the effect or problem identified.
- **D5: Verify Permanent Corrections (PCs) for Problem will resolve problem for the customer:**
  - Using pre-production programs, quantitatively confirm that the selected correction will resolve the problem. (Verify that the correction will actually solve the problem.)
- **D6: Define and Implement Corrective Actions:**
  - Define and Implement the best corrective actions.
- **D7: Prevent Recurrence / System Problems:**
  - Modify the management systems, operation systems, practices, and procedures to prevent recurrence of this and similar problems.
- **D8: Congratulate main contributors to your CAR team:**
  - Recognize the collective efforts of the team. The team needs to be formally thanked by the organization. 8Ds has become a standard in the automotive, <sup>[1]</sup> assembly, and other industries that require a thorough structured problem-solving process using a team approach.

## Philosophy



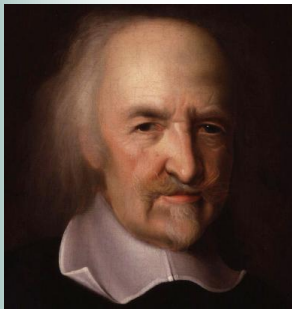
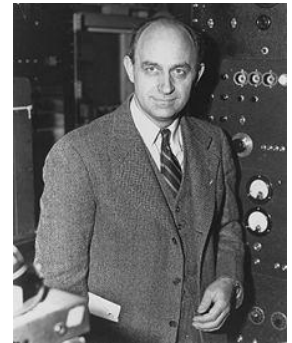
**Law of the instrument:**

*"I suppose it is tempting, if the only tool you have is a hammer, to treat everything as if it were a nail."*

Abraham Maslow

*"If the result confirms the hypothesis, then you've made a measurement. If the result is contrary to the hypothesis, then you've made a discovery"*

Enrico Fermi



*"For between True Science and Erroneous Doctrines, Ignorance is in the middle."*

Thomas Hobbes

*"All models are wrong but some are useful"*

George E.P. Box



# QRING Confirmation Bias

- To better accept the unknown
  - *try catching it using two or more sensor types.*
    - Use sensors of different make and design, e.g. accelerometer, laser vibrometer, proximeter, etc.
- Collect and systemize data
  - Register data 24/7
  - Automate processing
    - *Put the effort into understanding results instead of on generating the plots/tables.*
- Structured analysis process
  - Start from the helicopter view
  - Dive into detail only for a defined purpose, i.e. to examine a hypothesis.
- Embrace sensor 'errors'
  - First make sure the sensor is working as it should
  - Next, explain why it is behaving strange – *this may well be the key to unlocking the mystery.*



# Example:

## *V4 Dieselmotor Waterpump*

*Importance of differences in knowledge basis,  
combining geometry with data (ODS),  
the use of a 'wasteful' attitude to  
measurement channels  
&  
the value in buing a friend lunch*

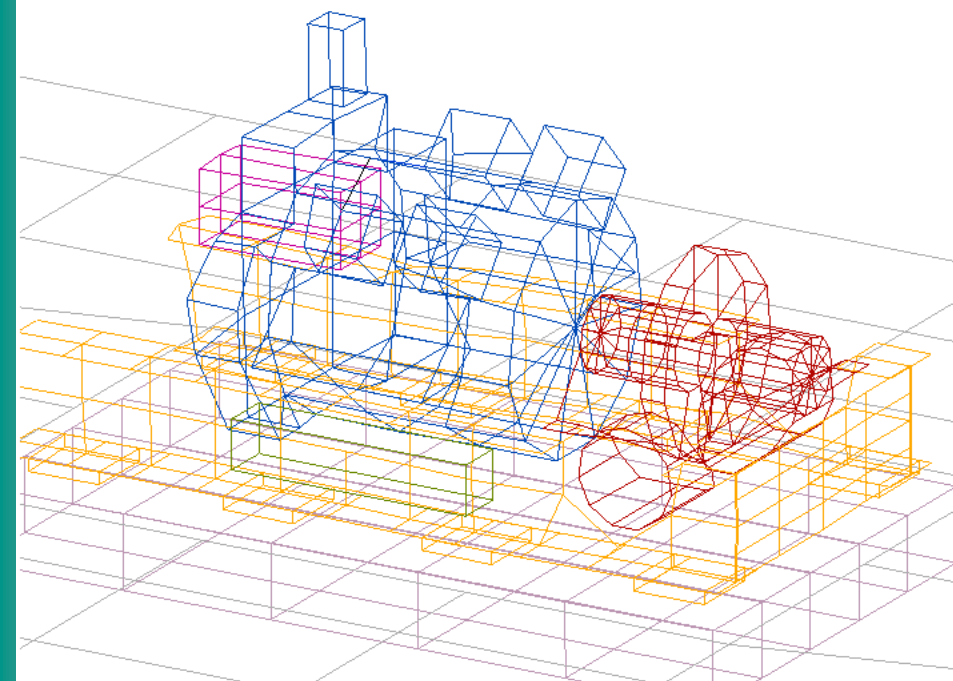
# Problem

- Very high vibration levels,
  - 5g , 25000 mm/s RMS
- Poor auxiliary equipment uptime
- The unit
  - Was taken apart, balanced & renovated.
  - End result => ***higher vibration***

# QRING 178 Ch Realtime Measurement

High *axial* direction vibration 2xRevolution?

Time (sec): 4.056514

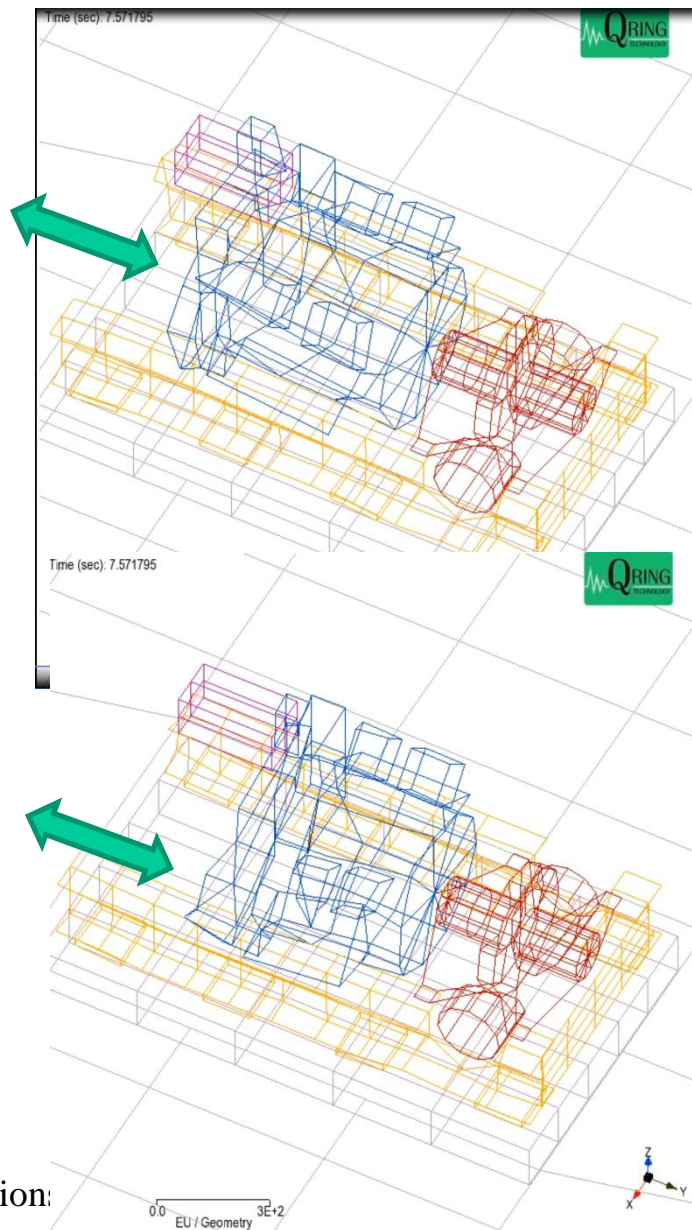


Qring just wanted to test drive a larger measurement setup and did not believe it to be problem relevant.

As it turned out – *realtime data mattered.*

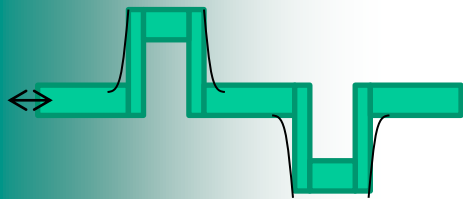
2017-11-08

Vibration in Nuclear Application:



## What it all boiled down to

- The V4 motor design was old, from the 1940's.
  - The V4 design was troublesome from day 1 according to the supplier.
  - Findings were submitted to the usual network but satisfactory explanation could not be found.
  - A motordesigner from another company explained the situation to Qring (over lunch)
    - "Choose the wrong firing order for the V4 geometry."
    - "Have a bending weak crank web."
    - "And - this is what you end up with, i.e. it is a design flaw & not the way to build a V4 diesel."
- Options:
  - *Replace* with other, better, motor.
  - *Robustify* motor auxiliaries for coexistence with the existing motor.





# Example:

## X-ray Machines

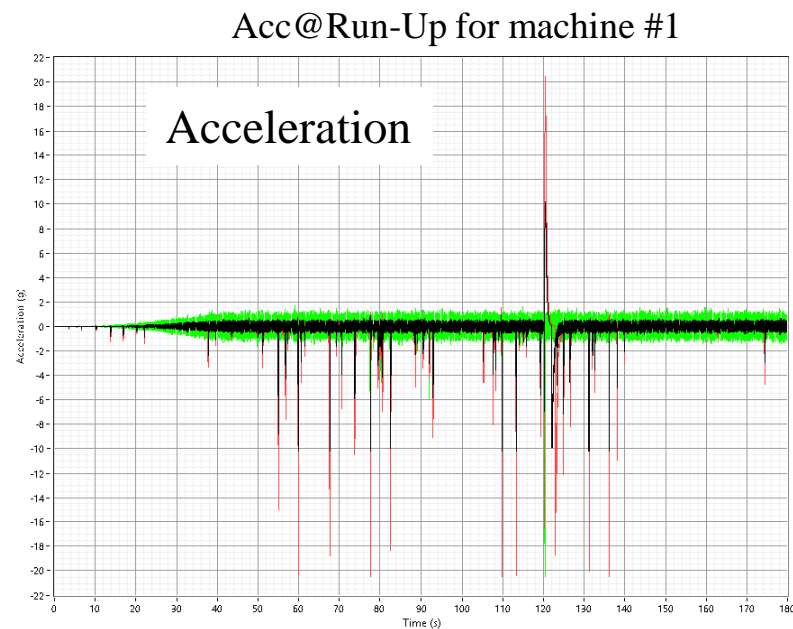
*Importance of different sensor types  
&  
a 'wasteful' attitude to data collection*

# Problem & Measurement

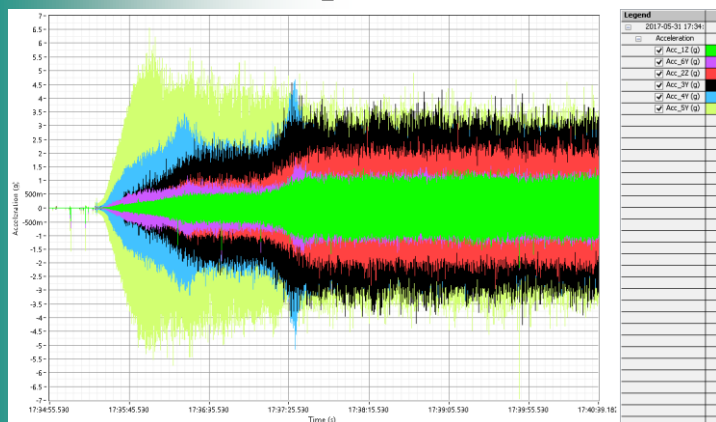
- The machines work,
  - But, sometimes get stuck and refuse to start.
  - A hand push in the reverse rotation direction & it starts.
  - Bearing damage was suspected. Replacing the bearing is complicated.
- Measurement of
  - Vibration with accelerometers and laser vibrometer,
  - RPM with optical tacho,
  - AC current
  - Sound using microphone.
  - Voltage with 2-ch 40 MHz oscilloscope.
- Time signal, (ODS & Order) analysis

# QRING Run Up

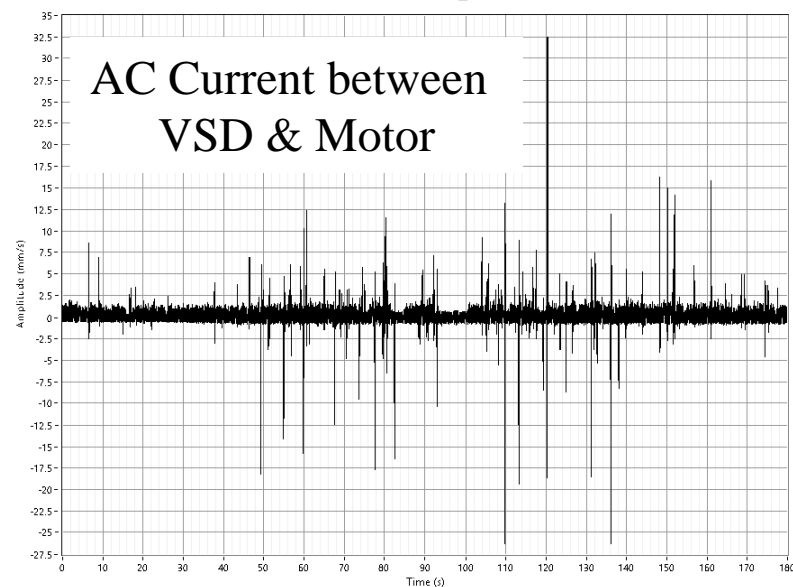
Strange acceleration spikes appear during Run-Up for one of the machines.



Acc@Run-Up for machine #2

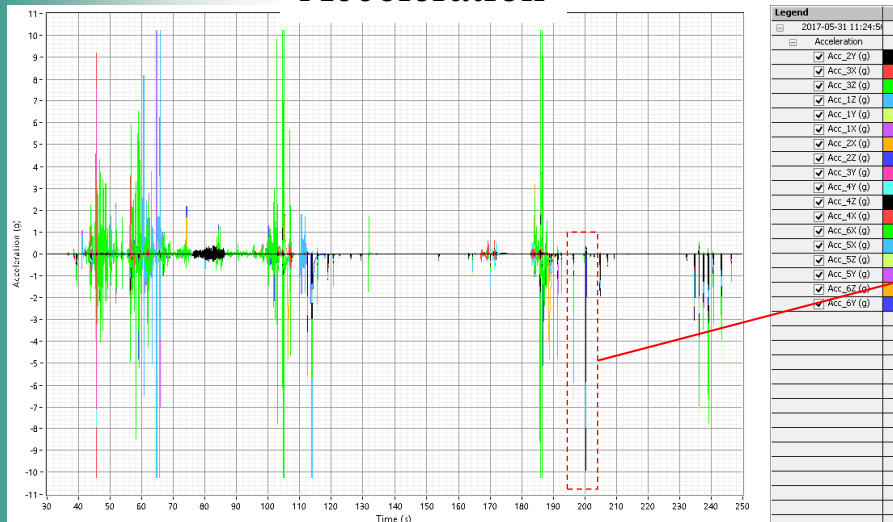


Current@Run-Up for machine #1

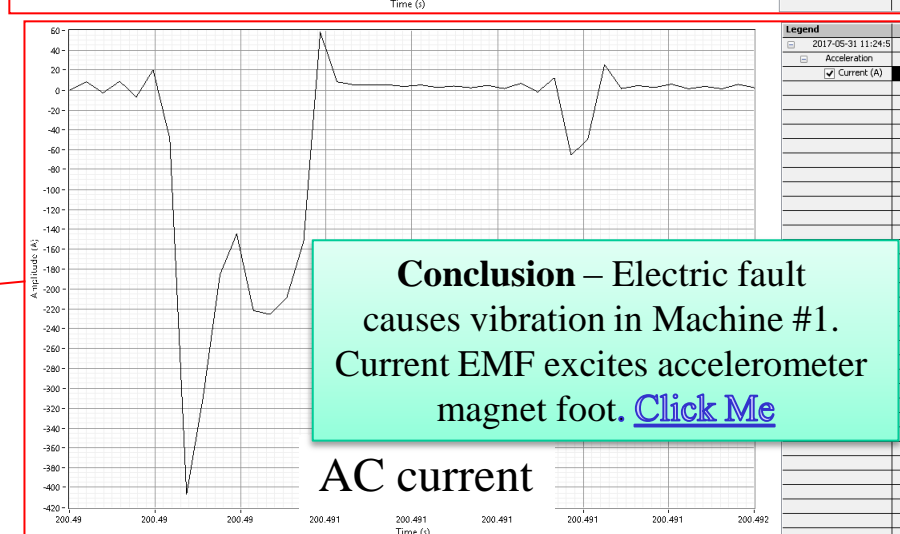
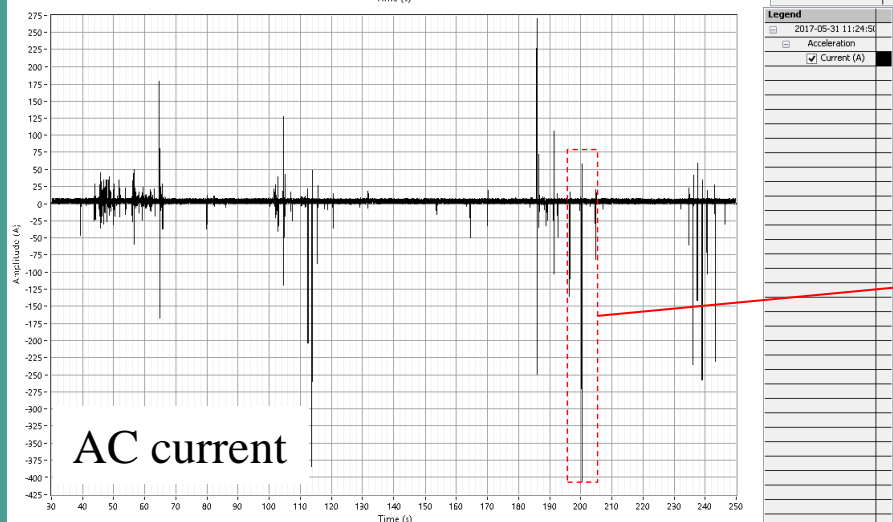
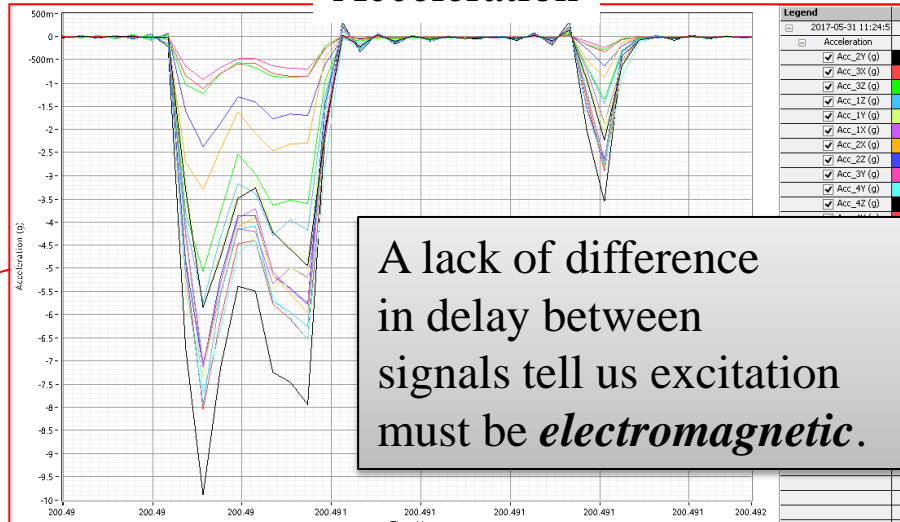


25,600 Samples/s

Acceleration



Acceleration



# Example:

## Centrifugal Flue Gas Fan & Variable Speed Drive (VSD)

*Importance of differences in knowledge basis,  
logging data for a long time,  
multi-sensors  
&  
automating the processing*

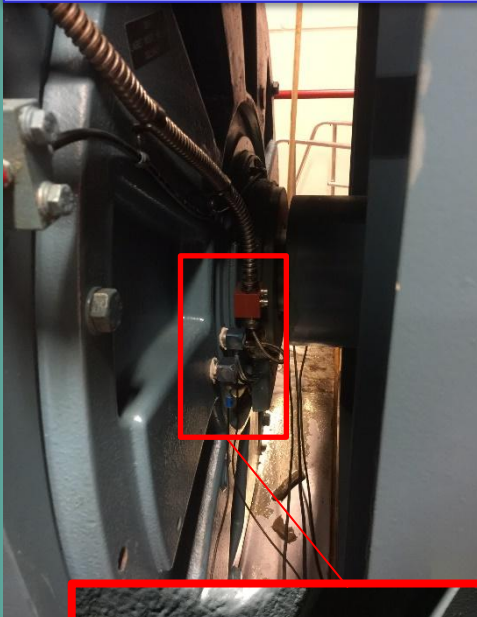
# Problem

- A broken 1,7 MW flue gas fan
- Problem solving involved
  - Soft feet, alignment
  - Momentary strong axial vibration
  - Torsion vibration
  - Process control – PID regulator
  - High Frequency ground potential
  - VSD control software theory



## Accelerometers

Acc Motor NDE



Acc Motor DE



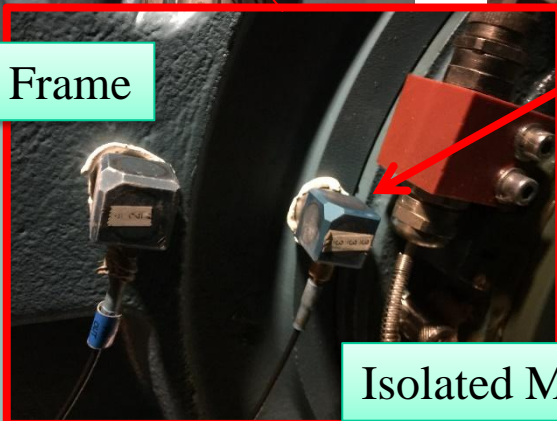
Acc Fan DE Bearing



Acc Floor



Motor Frame



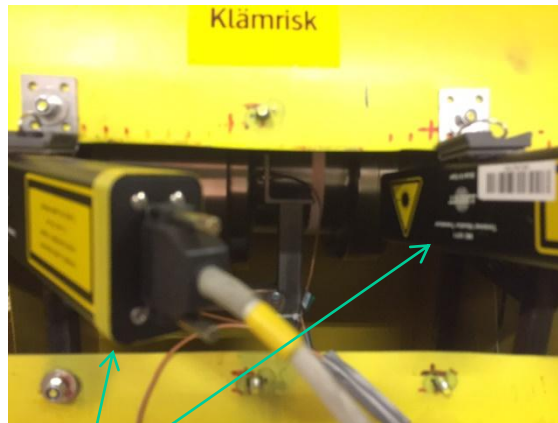
To be discussed

*Accelerometer design is grounded.  
The setup uses epoxy to isolate  
magnet base, plus epoxy for gluing.  
A setup involving a large  
isolating pad was tested with  
the same end result.*

Isolated Motor Bearing

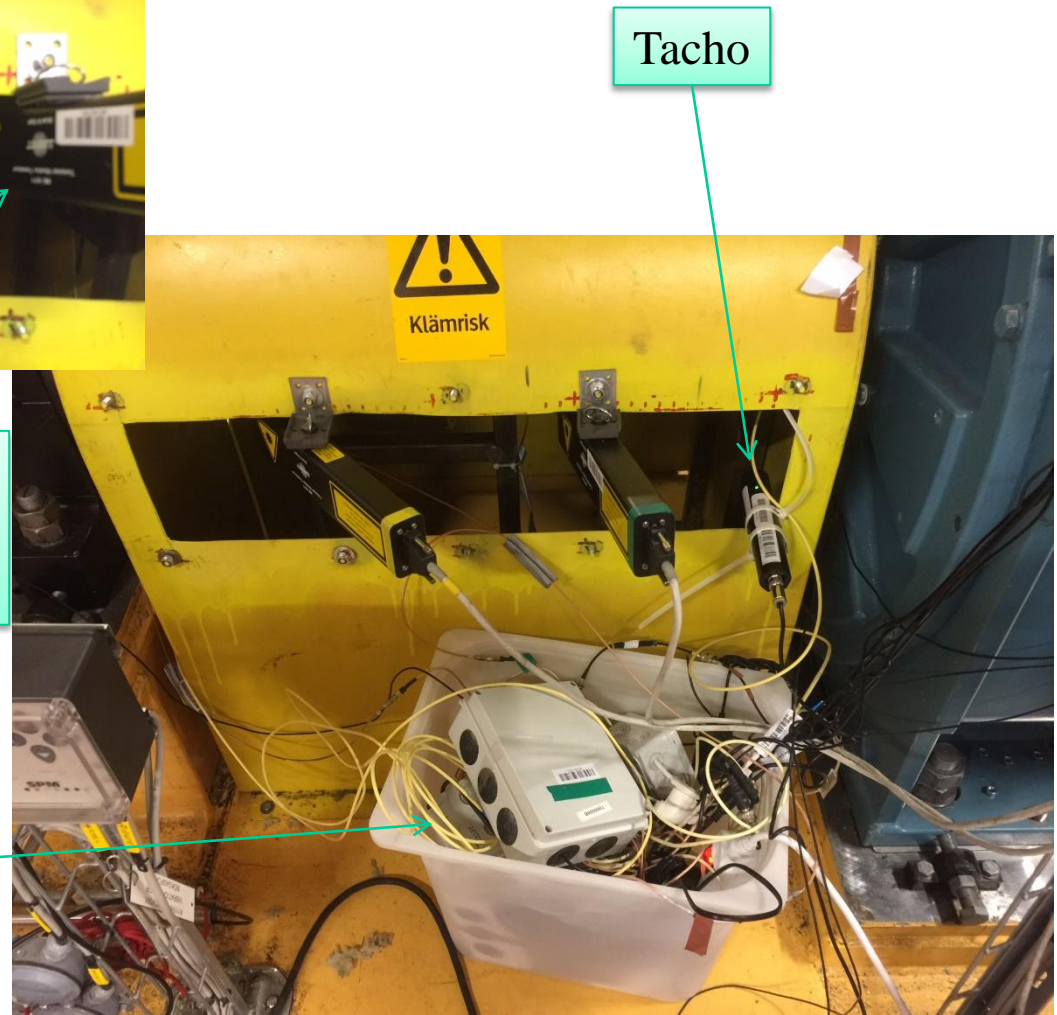


## Lasers, Tacho & Proximometers inside cover



2xTorsion lasers as there is a flexible coupling between the fan Drive End and the motor DE.

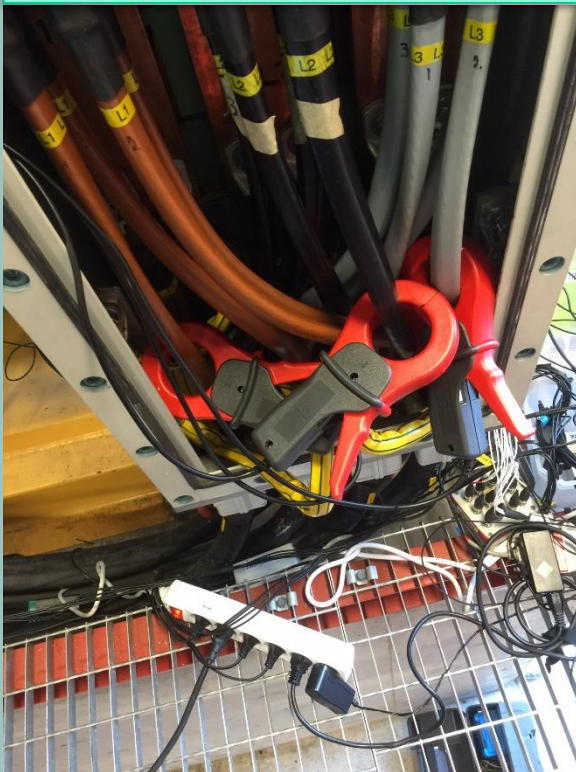
Proximiter probes to measure support-shaft motion.



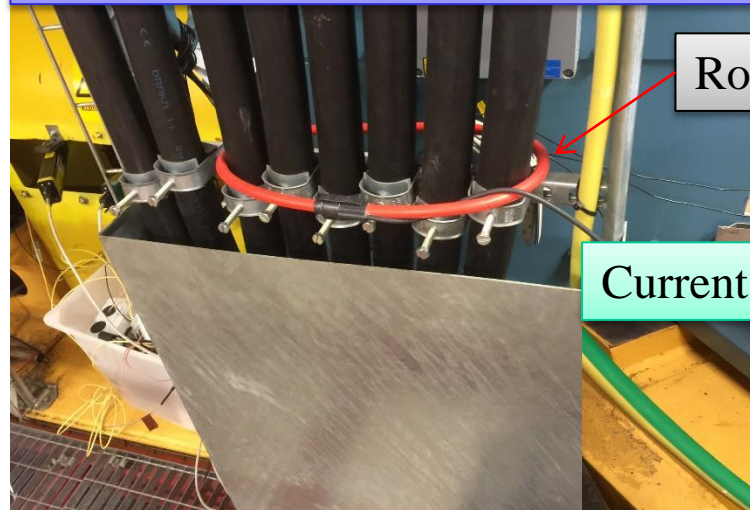


## Current

L1-L3 Motor Current

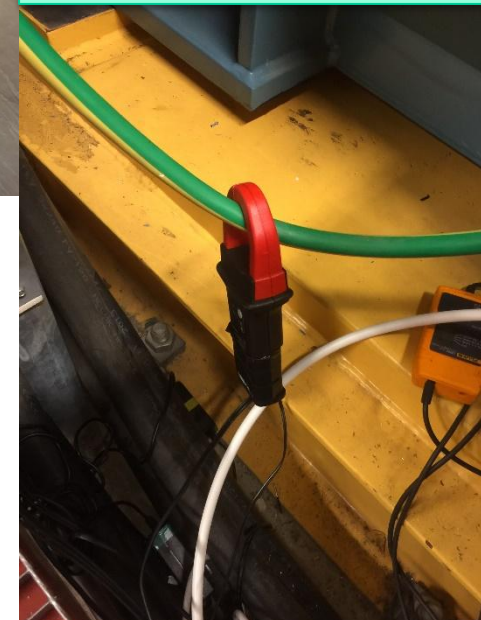


Summed Current@Motor  
(L1+L2+L3+N+Gnd)



Rogowski Coil

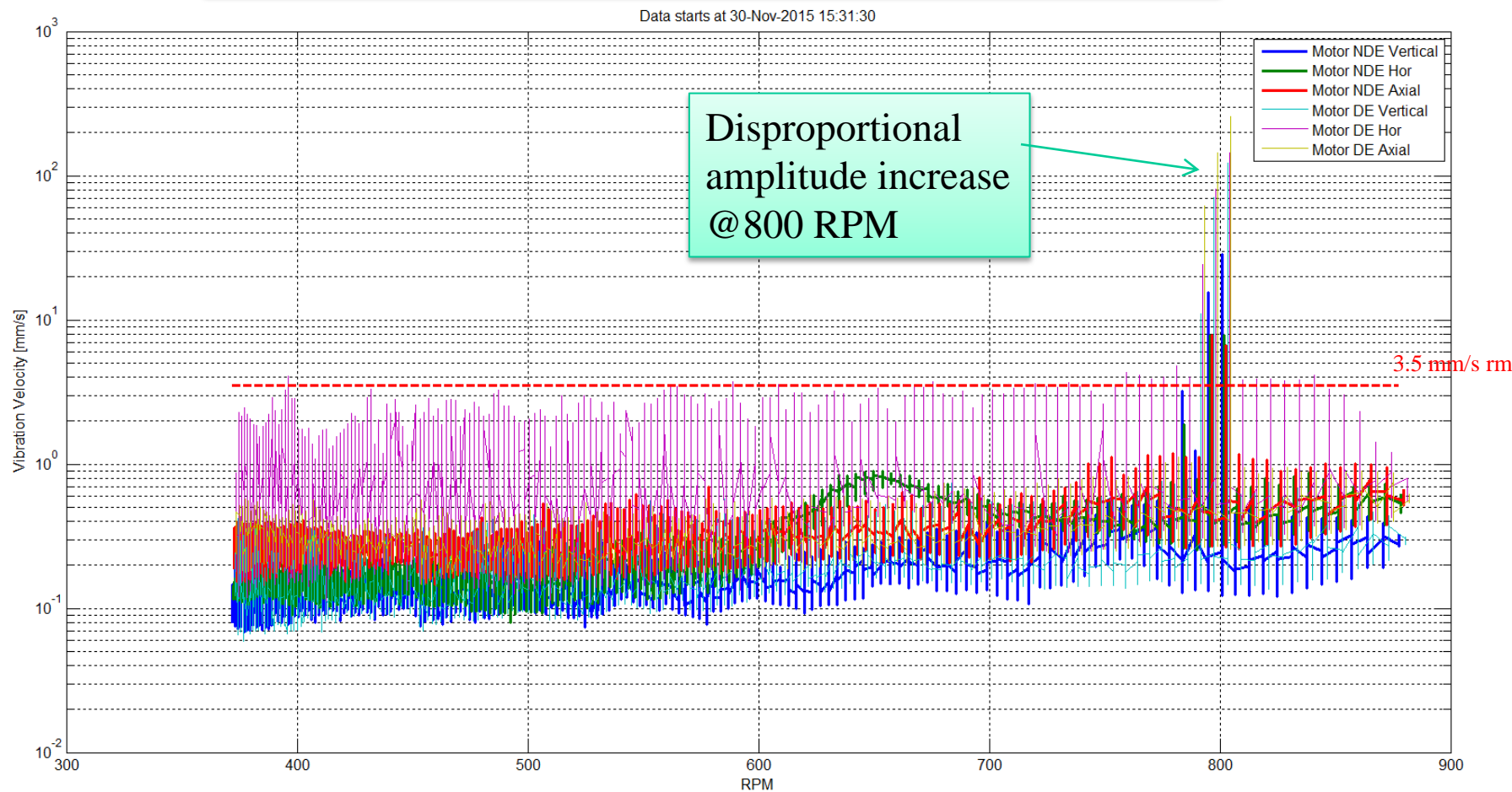
Current Ground



Also,  
Summed Current@Network  
was measured using a  
Rogowski Coil

# Motor Bearing

Data collected 24/7 for a few weeks to get full speed range.

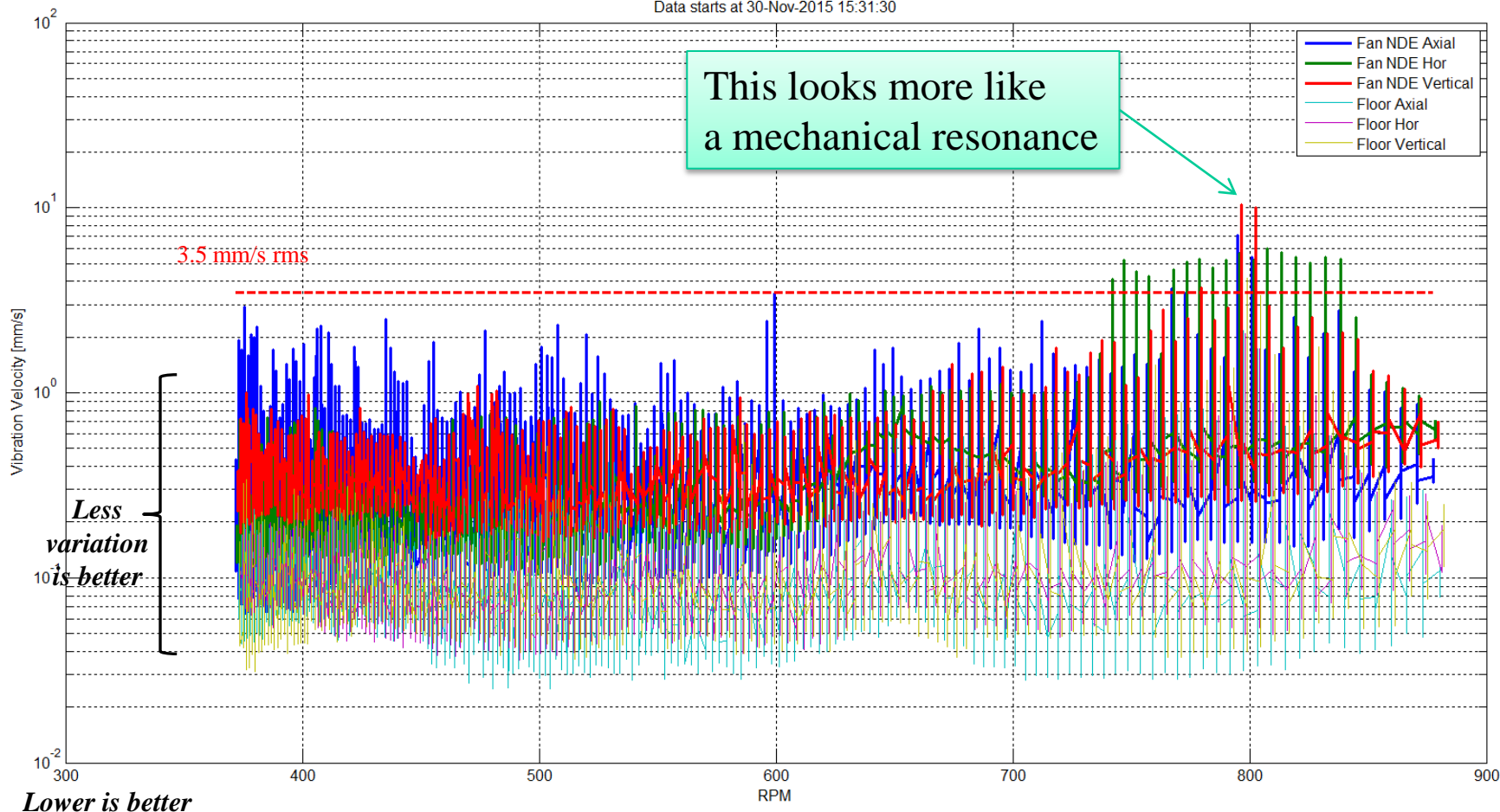


## Motor Supports and Floor

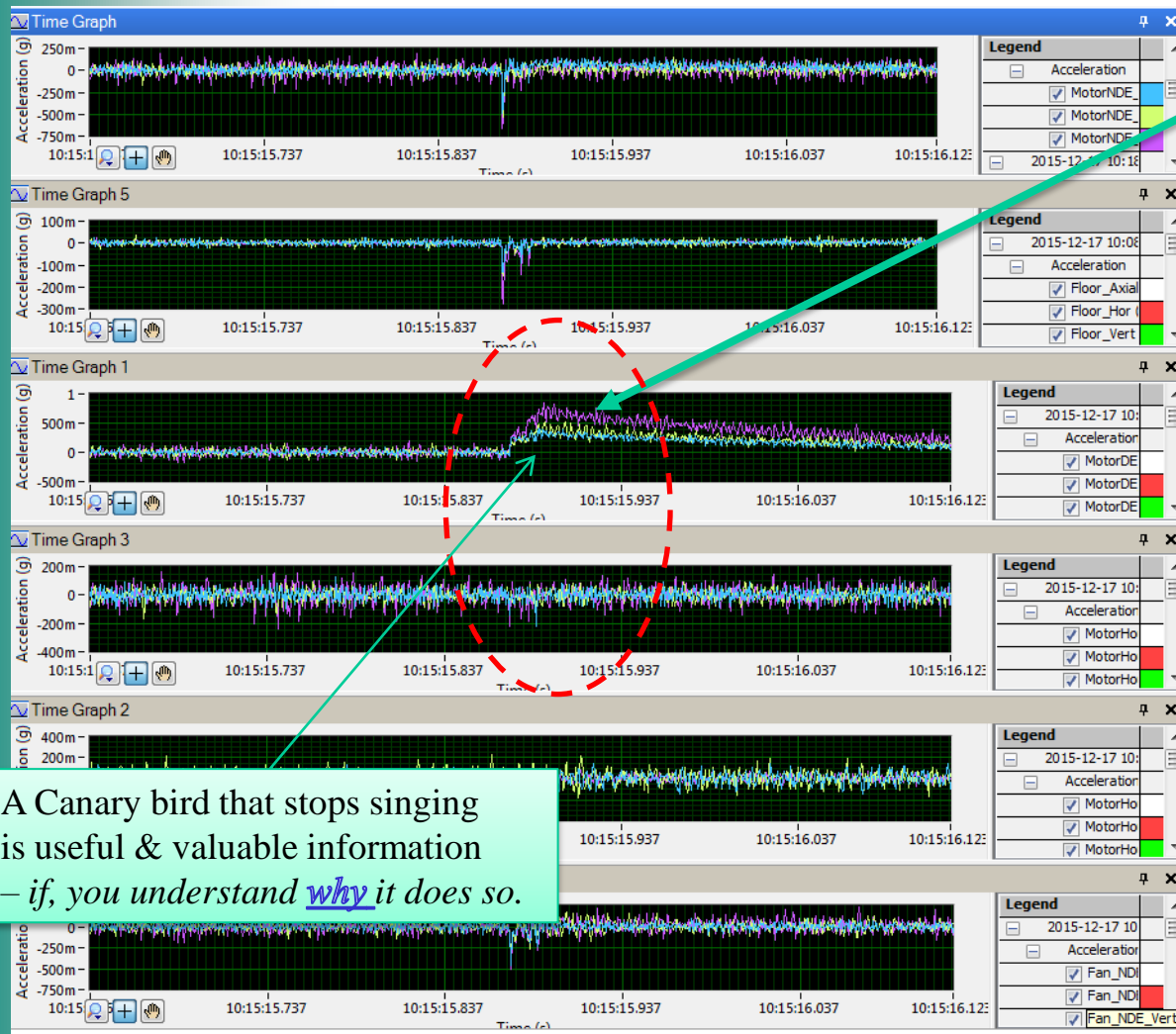
Data collected 24/7 for a few weeks to get full speed range.

*Higher is worse*

Data starts at 30-Nov-2015 15:31:30



# QRING Canary bird: Measurements?



A Canary bird that stops singing is useful & valuable information – if, you understand *why* it does so.

The Acc signal suddenly DC shifts  
**Why?** - a high frequency induced ground potential becomes large enough for a spark to jump from bearing to acc ground.

**SMARTNEWS** Keeping you current

## The Story of the Real Canary in the Coal Mine

Used until just 30 years ago, the humble canary was an important part of British mining history

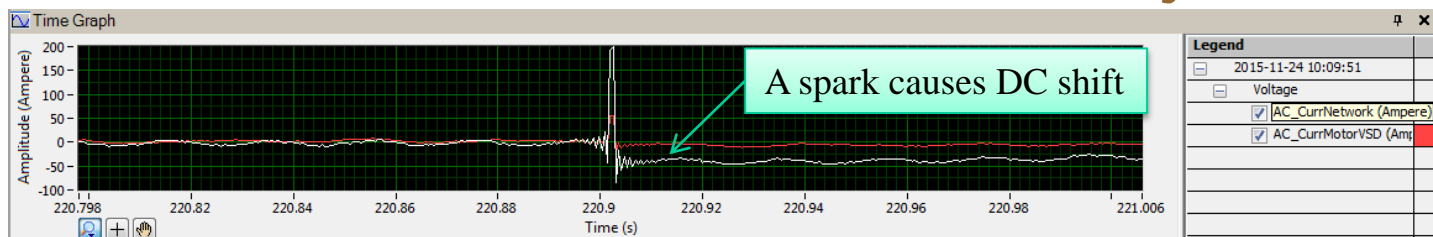


Mining foreman R. Thornburg shows a small cage with a canary used for testing carbon monoxide gas in 1928. (George McCaa, U.S. Bureau of Mines)

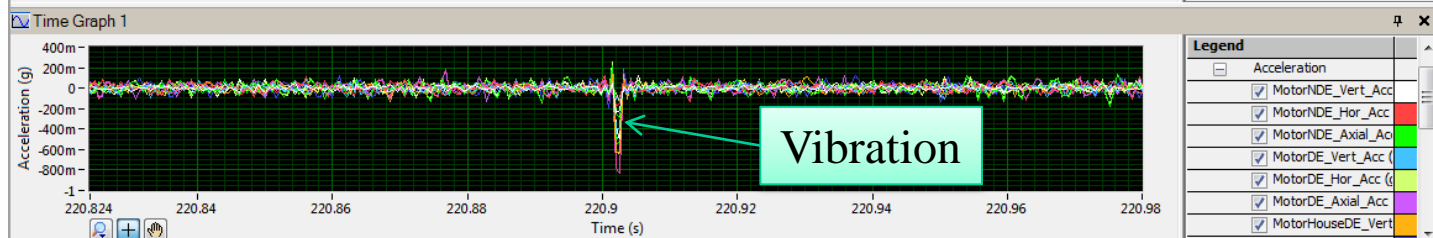


## Multidisciplinary: *The VSD causes sudden jerks*

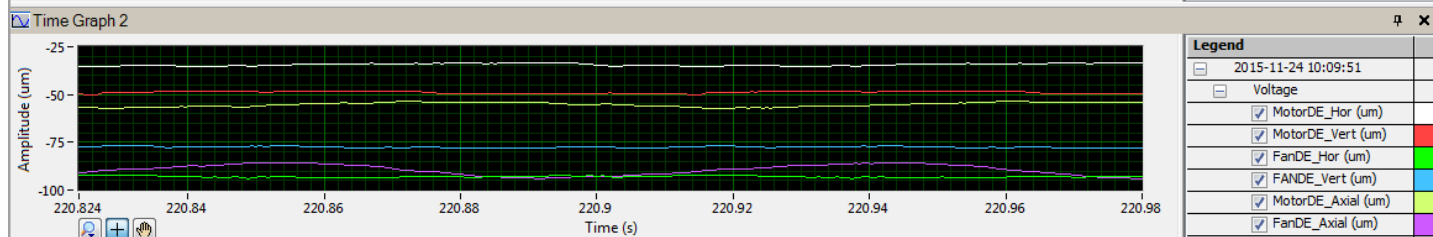
AC current  
(Rogowski Coils)



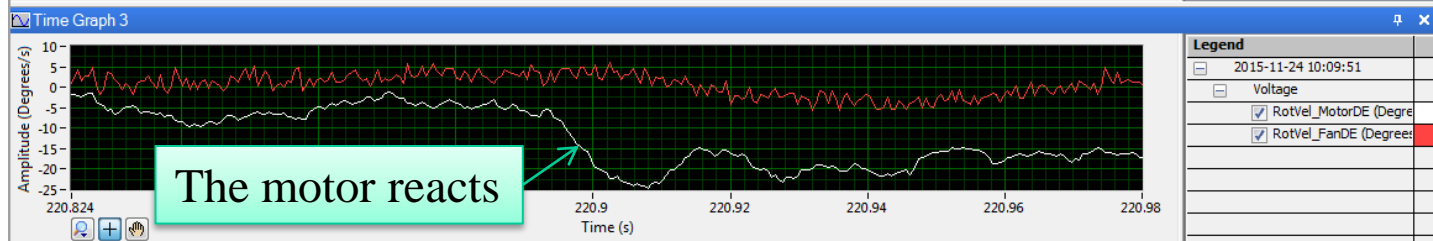
Vibration



Relative position  
(prox)



Torsion  
(a flexible coupling  
is located between  
fan & motor)



Automated processing was used to identify and analyze erratic behavior.

# What it all boiled down to

- Axial vibration.
  - The ground floor triax showed 1000 mm/s which pointed out another fan, a few rooms away to be the culprit.
- Torsion
  - Showed the presence of two backward rotating modes that sometimes were excited.
- Voltage sparks.
  - The VSD 360° grounding was incorrect & caused electric discharge (sparks).
- Variable Speed Drive (VSD) software theory
  - Only caters for RPM, *cannot use*
    - *Key phase (Tacho) information, i.e. is unable to sense if it is reglulating too late.*
    - *Encoder A or B channel, but not both, i.e. is unable to sense jerks.*
  - Therefore, the VSD is fooled by BW rotating modes that phase shift key phase  $N \cdot 180$  degrees - which also trigger sparks
- Solution
  - Trim down VSD PID settings and use S-ramp.
  - Reduce step size and avoid jumps in setpoint gradient

## Example: Axial Flue Gas Fan

*Importance of differences in knowledge basis,  
use of a multi disciplinary approach,  
logging data for a long time,  
use of built in sensors,  
grabbing past/present control room data,  
a recapture of prior knowledge  
&  
customized processing*

# Problem & Work

- The fan
  - had after many years of operation experienced two failures.
  - was suspended from rubber blocks who were believe to be faulty and one end had been fitted with metal blocks.
- Correlation vibration versus certain boiler MW ranges was known.
  - Otherwise hard to predict or understand the fan or what to do about it.
- Work:
  - EMA, Torsion vibration measurement at unexpected outage
  - 3 month operation 24/7 logging of
    - Vibration
    - AC summed & ground current
    - Oil pressure
    - Channel pressure
    - Blade Angle



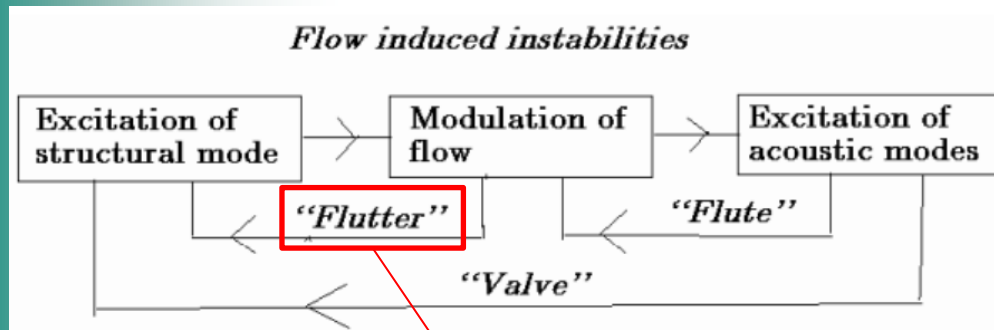
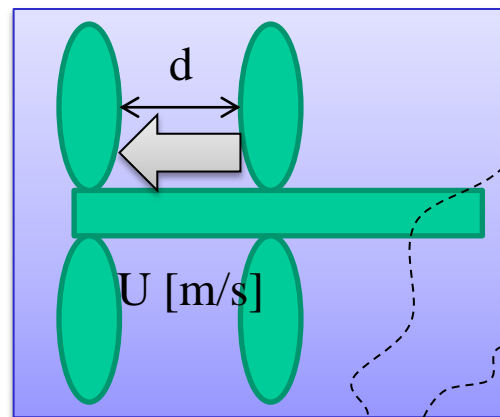


Figure 8.7: A classification of flow induced instabilities.

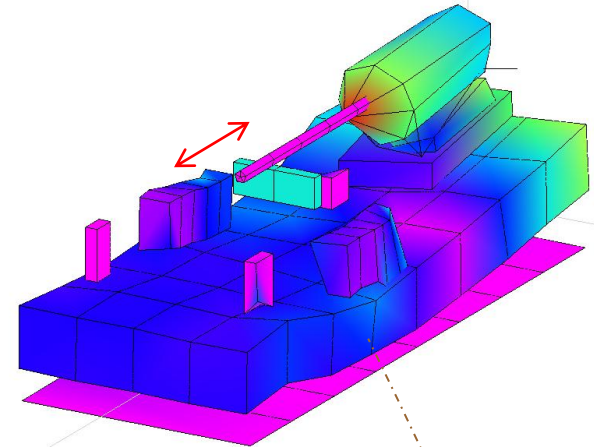
Axial flow frequency

$$f_{flow} = U/d \text{ [Hz]}$$

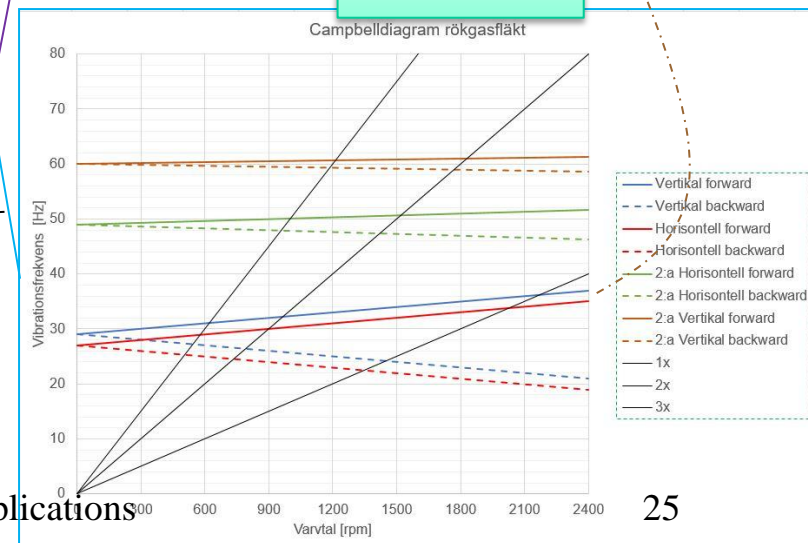


Flutter

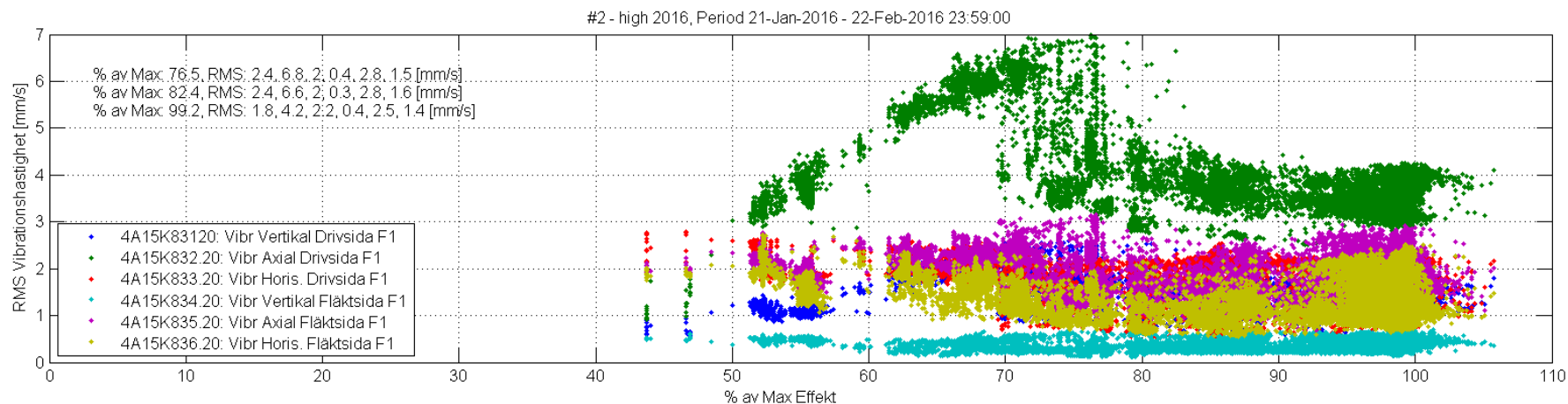
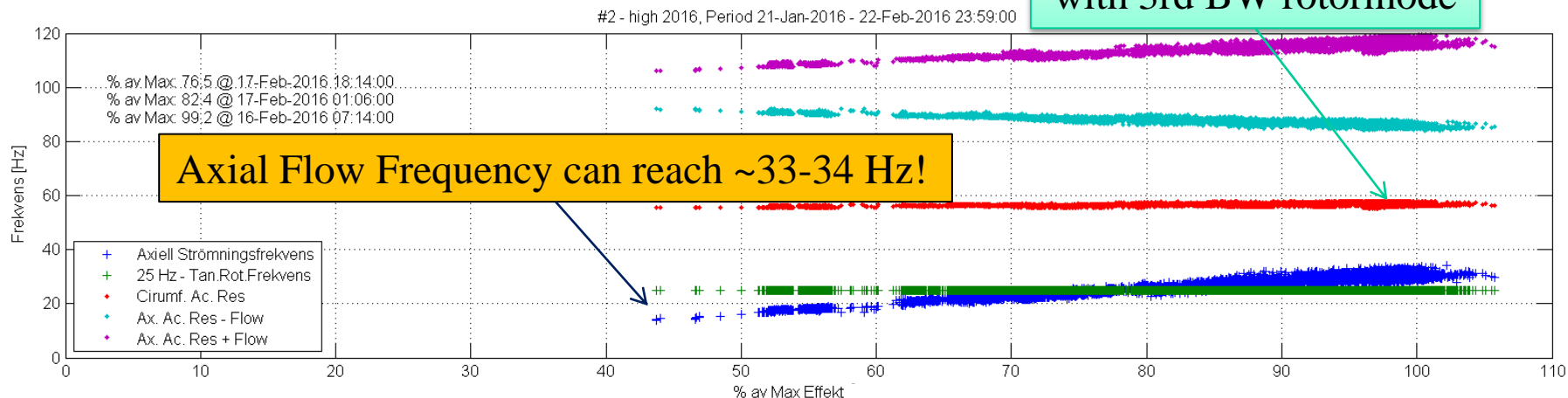
Block Bending Mode@27 Hz



Modal interaction



Acoustics may interfere with 3rd BW rotormode

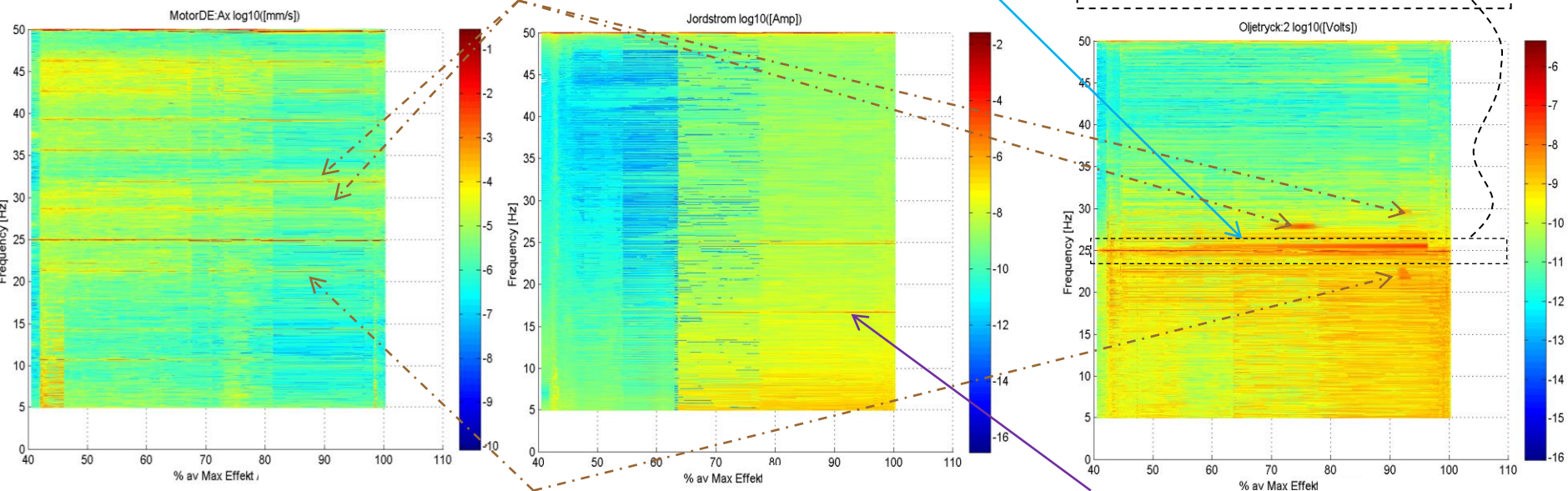


## Bespoke Processing: *Frequency-%Max Boiler Pwr-EU*

Complex fan behaviour  
- *a lot of things are going on*

FW rotating modes

Block  
Bending



BW rotating modes

1xMotor phase unevenly loaded when flow frequency exceeds motor rotation frequency

# What it all Boiled down to

- Fan is costly to service
  - Therefore, is intended to be replaced by a more modern fan design in a few years time.
  - The fan was repaired with several new parts.
  - Faults from prior failure were corrected.
  - Motor was disassembled and a loose part found.
- The project work
  - Recaptured some old knowledge
  - Was used to guide and improve repair work.
  - Insights serve as a phenomenological map.
  - Provides operators with new avoidance recommendations that differ from one operating regime to the next.
    - What is a correct action in one regime is wrong in the next.

# Example:

## Hydropower Kaplan Turbine

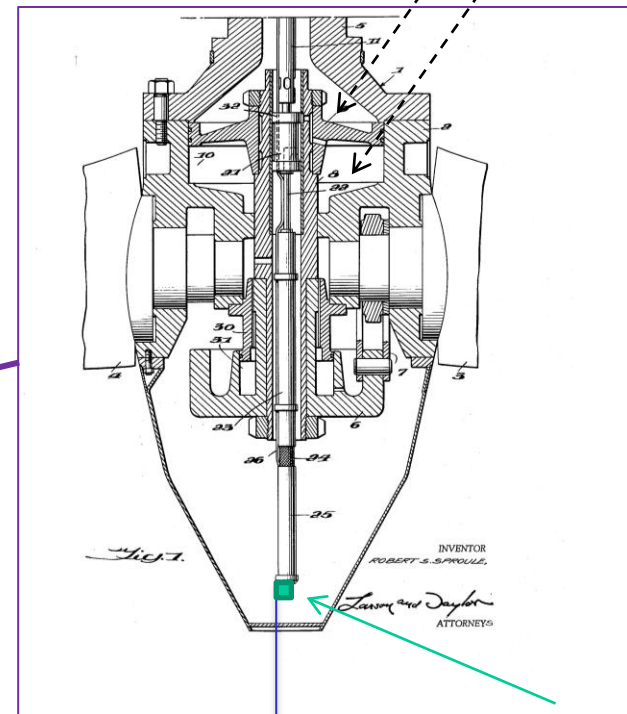
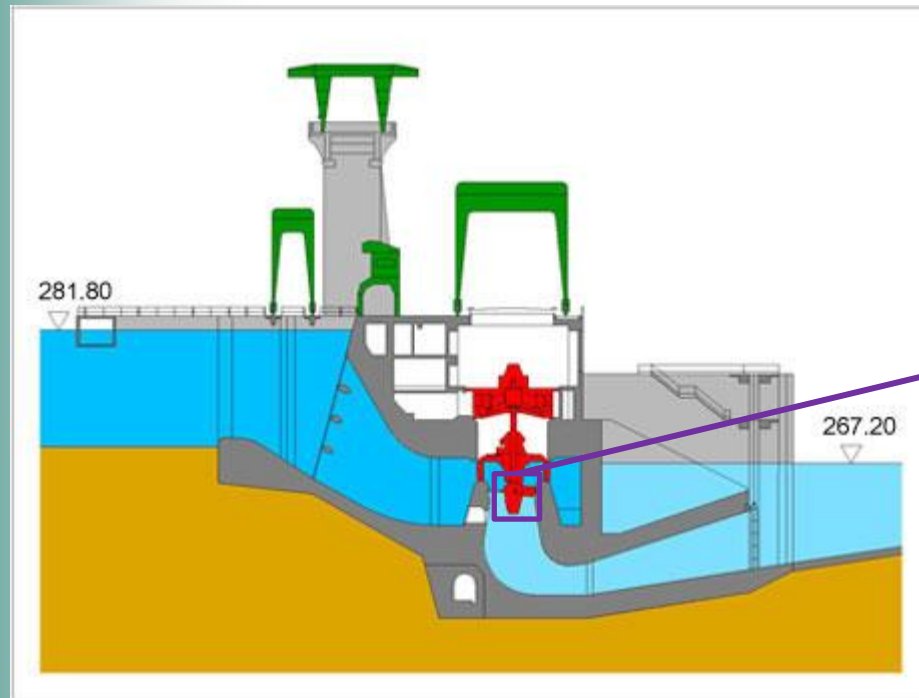
*Importance of multi-sensors,  
multiple dataviews  
&  
automated processing*

# Problem, Suspicion & Work

- Capacity
  - Hydraulic control consumed a large portion of the available pressure.
- Stick-slip
  - Suspected as control behaved erratic.
- Measurement
  - Acceleration
  - Position using string-wire gauge,
  - Pressure
  - Pulsation.
  - Orientation using inclinometer + Interial Measurement Unit *(3dof DC acc, 3 dof gyro + 3dof magnetometer)*



## Measurement Setup



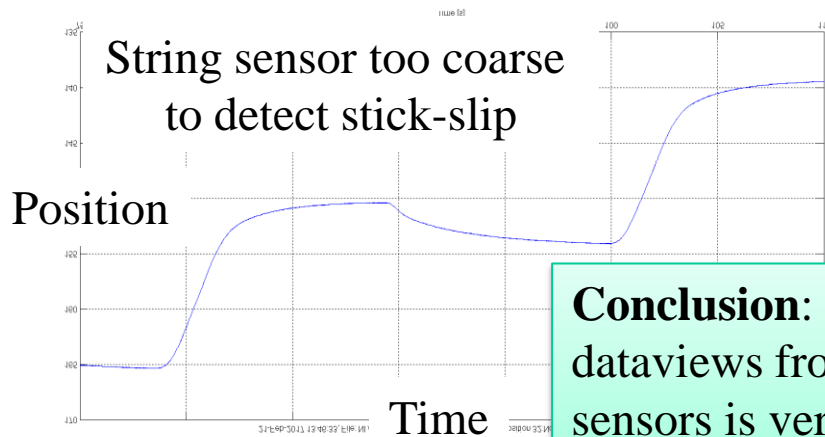
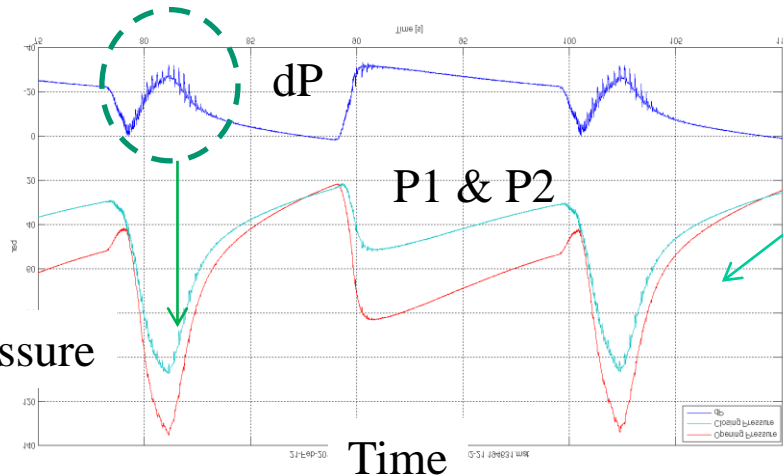
P1  
P2  
 $dP = P1 - P2$

String-wire  
Position Sensor

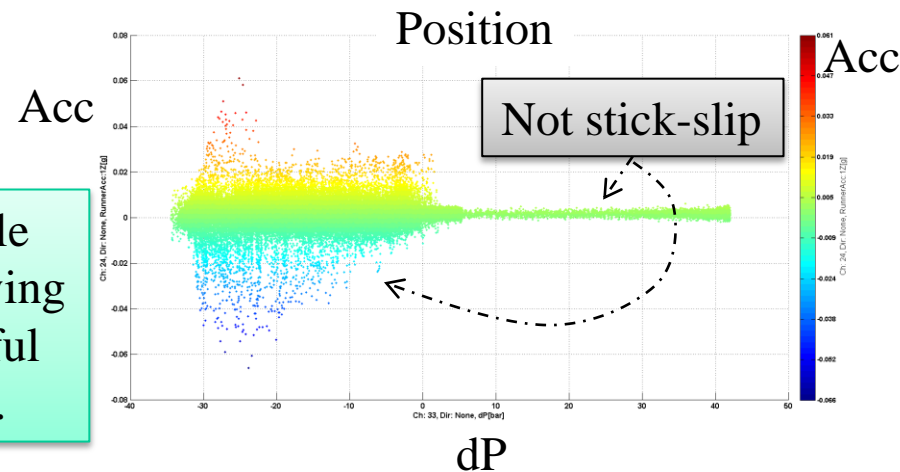
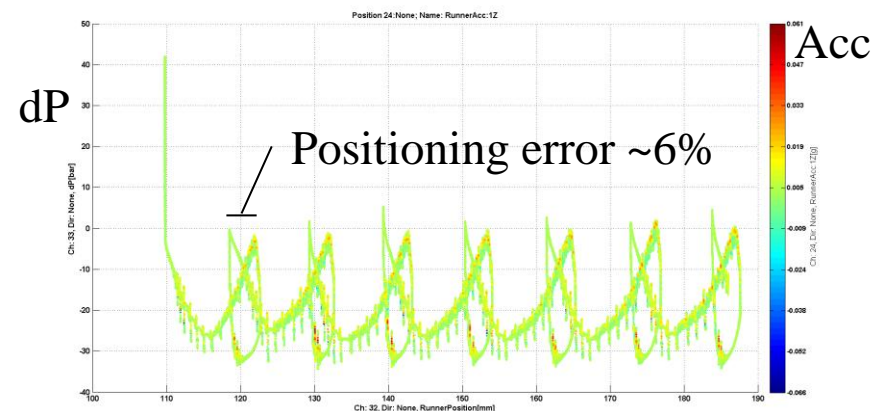
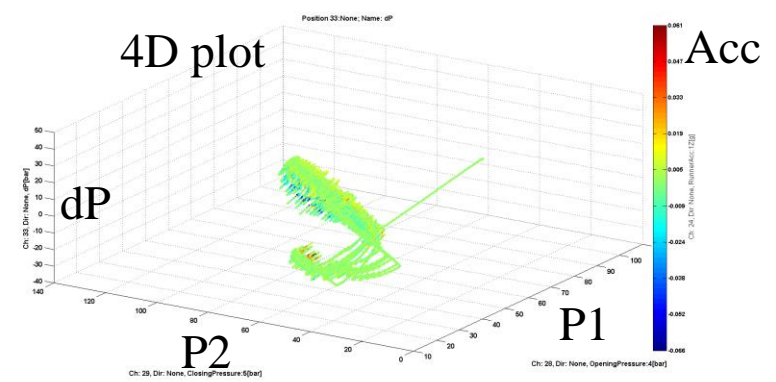
Acceleration

# QRING Data

?



**Conclusion:** Multiple dataviews from varying sensors is very helpful in the analysis work.





# What it boiled down to

- Stick-Slip
  - *Excluded* as it should be symmetric wrt to dP, predominant at low dP and as it does not explain the offset in both P1 & P2 regardless of direction.
- Explanation: Valve set points
  - Cause an offset in P1 & P2 and large hysteresis around zero dP.
    - One valve appears to stick.
    - Adjust valve set points.
- Consequence
  - A ~6% position error.
- Workaround
  - Adjust passive valve set points
  - Bypass arrangement until it works as intended.
- Data
  - Used for a variety of other, unintended, analyses, e.g. on mechanical tolerance, independent blade orientation measurement, etc.

# Summary

- Use a **shotgun approach**
  - **Measurement is cheap** – as compared to having problems
    - Use as many channels/sensors as practical
    - Use signals from built in sensors.
  - **Accumulate** as much data as practical
    - Measure 24/7 as long as motivated.
    - Use control room data.
  - **Team** to use differences
    - Gain as many views as possible & avoid confirmation bias.
- **Programmatic evaluation**
  - Use computer for the tedious work.
  - Output many data views & use at convenience.
  - Put the real effort into the understanding of data
  - *Turn strange sensor behaviour into knowledge.*



“The unnatural, that too is natural.”

Johann Wolfgang von Goethe